# Rules versus risk: Why perceptions of pedestrian comfort and safety differ for interactions with self-driven versus human-driven vehicles

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## **RESEARCH QUESTION**

Do pedestrian interactions with *self-driven vehicles* (SDV) evoke different topics than interactions with human-driven vehicles (HDV)?

### DATA

Deception-based survey to measure the *intrinsic* effects of vehicle autonomy (all else equal) on perceptions of pedestrian comfort & safety



#### **Topics significantly more likely to be discussed for SDV interactions (versus HDV)**



## **STRUCTURAL TOPIC MODELLING**

A regression method to infer latent topics in open text data & examine covariates of the: Topic Prevalence: how likely it is to be discussed

#### RESULTS

1. Vehicle should make a complete (not rolling) stop

2. Pedestrian agency and individuality of risk in a given situation

3. Importance of awareness and communication for pedestrian safety

4. Car need not yield if pedestrian not in crossing

5. Pedestrian should be aware and cautious before crossing

"The pedestrian did not check the traffic (look all ways). Is this because they expected the self-driving vehicle to stop?"

## FINDINGS

 Pedestrian interactions with self-driven vehicles (SDV) evoke comments on different topics than interactions with human-driven vehicles (HDV) • Evaluators focus on **rule compliance** for SDV, but focus on **risk mitigation** for HDV Pedestrians are ascribed more responsibility to be cautious, aware, and predictable when interacting with SDV

## **TO IMPROVE WALKABILITY IN CITIES WITH SDV...**

- SDV



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- Topic Content: words used to express each topic



Self-driven vehicles (SDV) should be programmed for strict rule compliance and conservative operation in city streets

Limit uncontrolled space negotiation between SDV and pedestrians

Enhance external communication from