Perceived safety and comfort of pedestrian interactions with self-driving vehicles

Recommendations for responsible introduction of self-driving vehicles

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ICTA-UAB



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INTRODUCTION

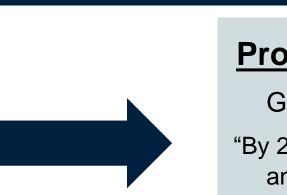




CONTEXT

- Public agencies have been promoting • active modes of travel
- Providing better facilities could ٠ increase active mode share
- But feeling <u>safe</u> and <u>comfortable</u> ٠ while travelling is also important

Better facilities for active mode users



Transport 2050:

"If people enjoy their transportation experience, they are more likely to travel..... A key part of this is feeling **comfortable, safe**, and secure when travelling"



Promote active modes

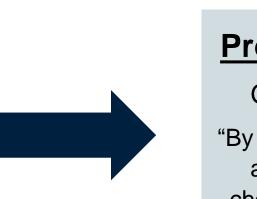
Goal of Transport 2050:

"By 2050, active transportation and transit are competitive choices accounting for at least half of all passenger trips."

CONTEXT

- In parallel to active modes, public • agencies are also promoting self-driving vehicles (SDVs)
- Both promotions are expected to align, • as SDVs could improve safety and accessibility

Better facilities for active mode users



"By 2050, connected and automated vehicles could be carrying a majority of passenger and freight trips in the region."

Transport 2050:

"If people enjoy their transportation experience, they are **more likely to travel**..... A key part of this is feeling comfortable, safe, and secure when travelling"



Promote active modes

Goal of Transport 2050:

"By 2050, active transportation and transit are competitive choices accounting for at least half of all passenger trips."

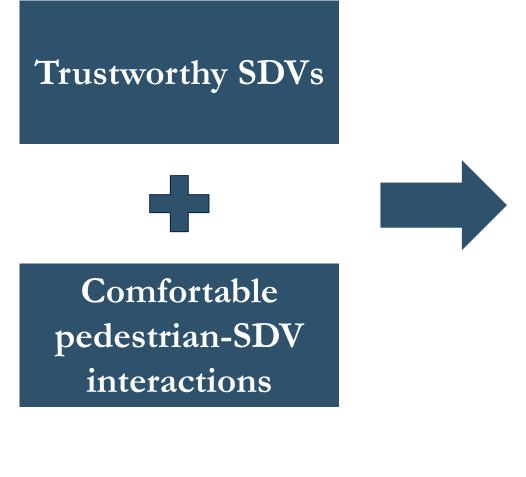
Promote self-driving vehicles (SDVs)

Transport 2050:

CHALLENGE

- For integrating SDVs responsibly

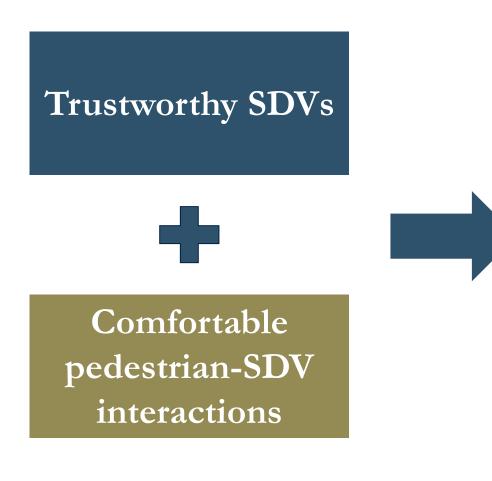
 (i.e., SDVs support active modes rather
 than degrade their experience), there
 are two components:
 - Having advanced, trustworthy SDV technology
 - Comfort of active travellers, including the quality of pedestrian-SDV interactions
- Perceptions of comfort and safety are crucial to responsible integration
 - Maintain walkable public streets
 - Influence acceptance/support for SDV integration policies



Responsible integration of SDVs into our transportation system

GOAL OF THIS STUDY

- Most focus up to now has been on SDV technology
- We focus on understanding pedestrian-SDV interactions so that:
 - We can propose realistic policies to inform a strategy for responsible introduction of SDVs
 - We can maintain quality of current walking experience in future



Responsible integration of SDVs into our transportation system

WE INVESTIGATE 3 RESEARCH QUESTIONS

Pedestrian-SDV interactions:

- Studies have examined how SDVs' communication or operational characteristics influence perceptions
- But no study has examined the core question: how does SDVs' defining characteristic – vehicle autonomy – influence perceptions?





WE INVESTIGATE 3 RESEARCH QUESTIONS (RQ)

- Do people perceive pedestrian interactions with **SDVs** as more or less comfortable and 1. safe than interactions with HDVs, controlling for all other differences?
 - (i.e., is there an "Autonomy Bias")?





WE INVESTIGATE 3 RESEARCH QUESTIONS

Pedestrian-SDV interactions:

- Perceptions are subjective
- Perceptions vary by personal attributes
- Perceptions influence SDV policy
 - responsible introduction of SDVs
 - We can maintain quality of current walking experience in future



WE INVESTIGATE 3 RESEARCH QUESTIONS (RQ)

- Do people perceive pedestrian interactions with **SDVs** as more or less comfortable and 1. safe than interactions with **HDVs**, controlling for all other differences? • (i.e., is there an "**Autonomy Bias**")?
- 2. Does the **Autonomy Bias** vary systematically within the **population** (e.g. with age, gender, race, travel habits, and so on)?
- 3. Which **personal attributes**, including Autonomy Bias, determine support for various **SDV policies**?



METHODS





SURVEY DATA

Survey was advertised on Facebook and Instagram ٠

Survey advertisement

We are looking for participants who travel in British Columbia to take our survey.

Participation requires between 10 and 15 minutes and involves viewing and rating a series of video clips of real-world interactions.

All participants will have a chance to enter into a draw for one of ten gift cards of \$25 each.

To participate, or get more information, please visit tinyurl.com/react-lab-survey...

Note that if you like, follow, or comment on this post, others may associate your profile with this study.



It was promoted by TransLink and UBC





UBC Civil Engineering @ubccivil · Oct 28 Dr. Alex Bigazzi & UBC REACT Lab are seeking #BC residents to participate in a survey on user-road interactions at crosswalks. Participants have a chance to win one of ten \$25 gift cards.

Take survey here: tinyurl.com/react-lab-surv...









- 1. Introduction and consent
- 2. SDV-related questions
 - Familiarity
 - Affective response (level of anxiety/enthusiasm) to SDV technology
 - \circ $\,$ Intention to ride in SDVs $\,$
 - Support for SDV policies







Support for SDV policies (strongly disagree to strongly agree):

Policies were realistic, relevant to pedestrians, comparable to literature, and useful for near-term decisions to introduce SDVs

SDV acceptance of SDV policies

- Allowing shared SDVs to operate on public roads
- Allowing **privately-owned SDVs** to operate on public roads

SDV operations and features

- Allowing SDVs to travel at the **same speed** as HDVs (vs. slower)
- Allowing SDVs to enter **pedestrian priority areas**, such as near schools
- Allowing SDVs to operate without a person in the driver's seat
- Allowing SDVs to operate without being clearly identified to other road users

- 1. Introduction and consent
- 2. SDV-related questions
 - Familiarity
 - Affective response (level of anxiety/enthusiasm) to SDV technology
 - \circ $\,$ Intention to ride in SDVs $\,$
 - Support for SDV policies
- 3. Deception-based experiment (interaction ratings)







1. Introduction and consent

Deception-based experiment:

- Familiarity
- Participants evaluate severity of interactions
 - Intention to ride in SDVs
- Vehicle described as "self-driving vehicle" or "regular vehicle"
- Both are (same) regular vehicles in reality
- All participants rate the same 8 videos



Regarding the interaction between the crossing pedestrian and the **self-driving vehicle** shown in the video, please indicate your level of agreement with the statements below:

Neither disagree nor Strongly Strongly Strongly disagree disagree agree agree -10 0 10 -10 🗖 I don't The vehicle yielded to the The drive pedestrian. pedestr know The vehicle should have yielded to I don't The drive the pede the pedestrian. know 🔲 I don't The pedestrian felt comfortable The ped in this cr in this crossing. know The risk of injury for the The risk L I don't pedestrian in this crossing was pedestri know low. low.



Regarding the interaction between the crossing pedestrian and the **regular vehicle** shown in the video, please indicate your level of agreement with the statements below:

Neither disagree nor agree 0	Strongly agree 10
rer yielded to the ian.	I don't know
•)
er <i>should have</i> yielded to estrian.	I don't know
lestrian felt comfortable rossing.	I don't know
•)
of injury for the ian in this crossing was	I don't know
•	

- 1. Introduction and consent
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 - Familiarity
 - Affective response (level of anxiety/enthusiasm) to SDV technology
 - o Intention to ride in SDVs
 - \circ Support for SDV policies
- 3. Deception-based experiment (interaction ratings)
- 4. Personal attributes
 - Socio-demographics (age, gender, income, race, etc.)
 - Travel habits (travel frequency using different modes)
 - Other personal attributes (risk aversion, early technology adopter, etc.)
- 5. Determine if deception was effective or not
- 6. Reveal deception and confirm consent







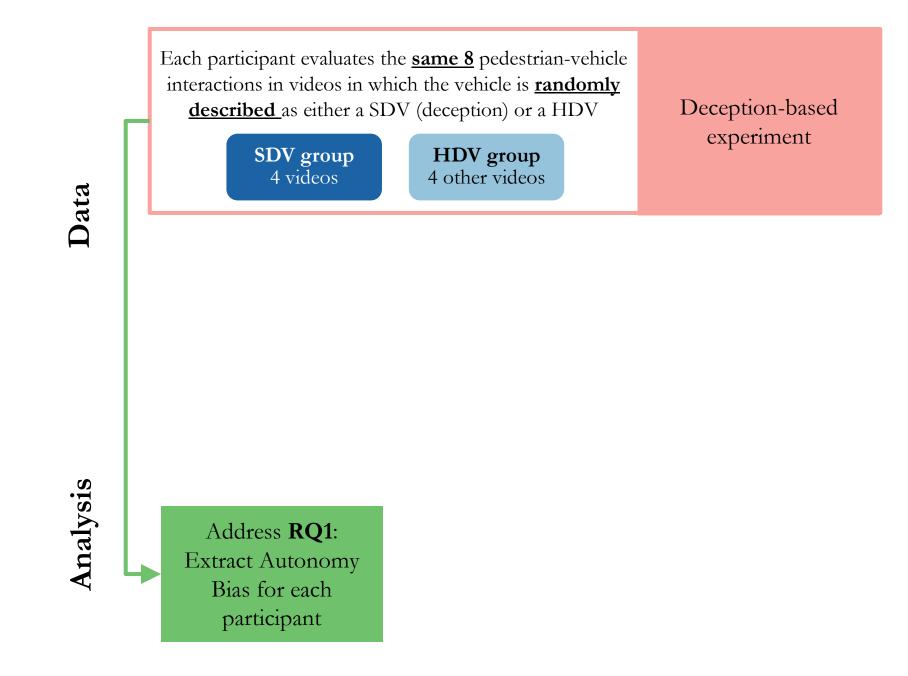
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- Personal attributes 4
 - Socio-demographics (age, gender, income, race, etc.)
 - Travel habits (travel frequency using different modes)
 - Other personal attributes (risk aversion, early technology adopter, etc.)

Determine if deception was effective or not

96% of the participants were deceived by our experiment, mainly because of their trust in authority (UBC researchers) and the SDVs in our videos meeting their expectations of SDV behaviour.



OVERVIEW OF METHODS









OVERVIEW OF METHODS

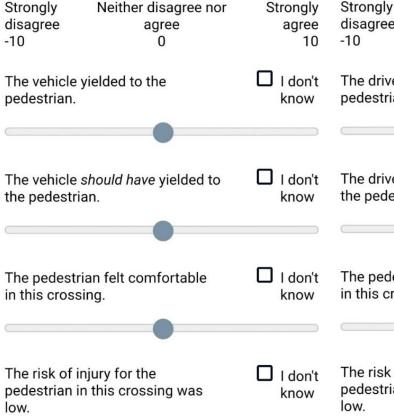
We observe Autonomy Bias from ratings:

- If a person has no Autonomy Bias, ratings of yielding, comfort, and safety should be same
- If a person has negative Autonomy Bias (i.e., bias against SDVs), they will rate SDV interactions as less comfortable and less safe than a HDV
- If a person has positive Autonomy Bias (i.e., bias *in favour of* SDVs), they will rate SDV interactions as more comfortable and safer than a HDV



Regarding the interaction between the crossing pedestrian and the **self-driving vehicle** shown in the video, please indicate your level of agreement with the statements below:

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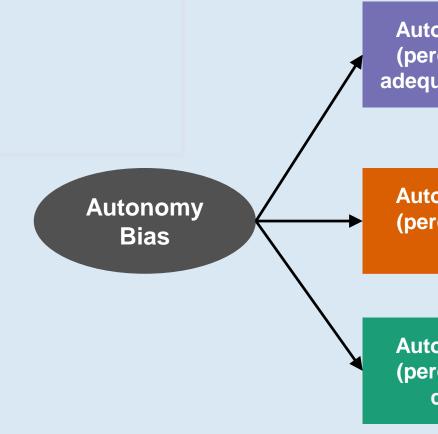




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- We conceptualize that the underlying Autonomy Bias influences how a person perceives yielding of the SDV, and safety and comfort of the crossing pedestrian (as shown by the direction of arrows).
- We use regression to extract each person's Autonomy Bias



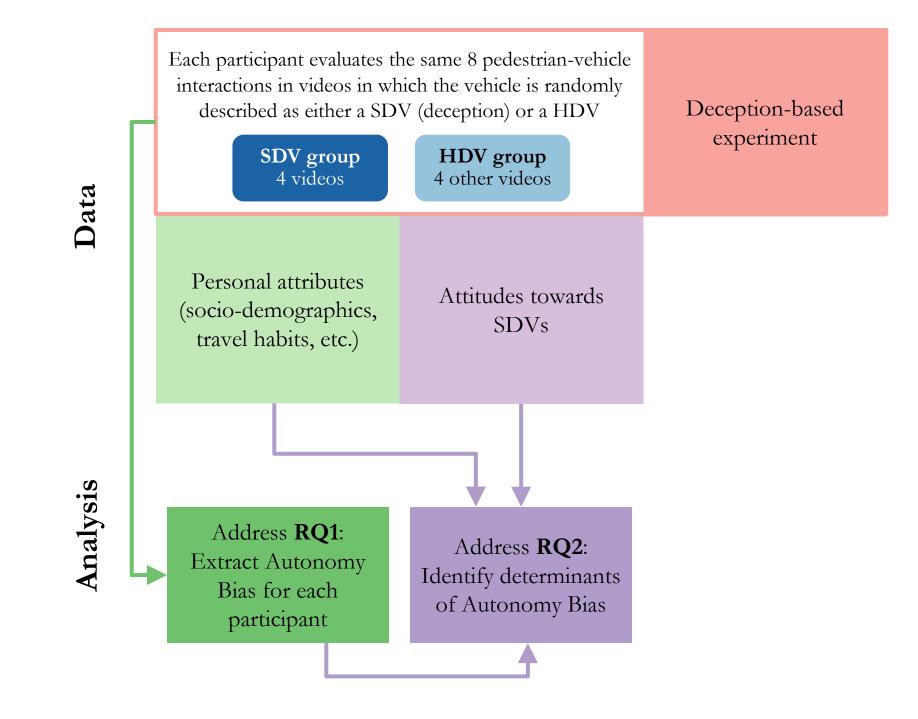
Autonomy Bias (perceptions of adequate yielding)



Autonomy Bias (perceptions of safety)

Autonomy Bias (perceptions of comfort)

OVERVIEW OF METHODS

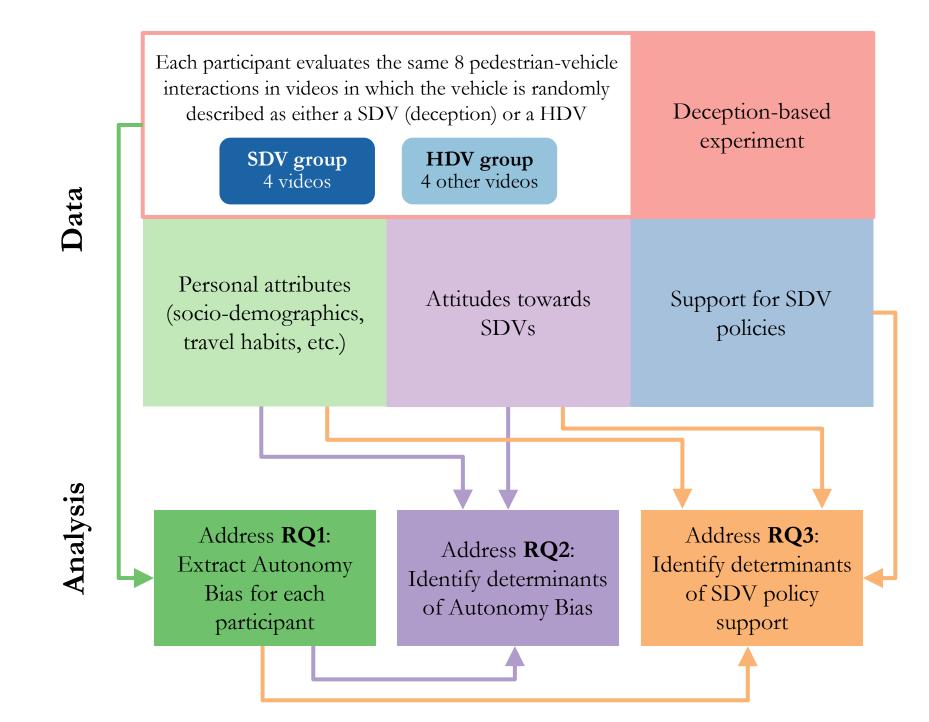








OVERVIEW OF METHODS







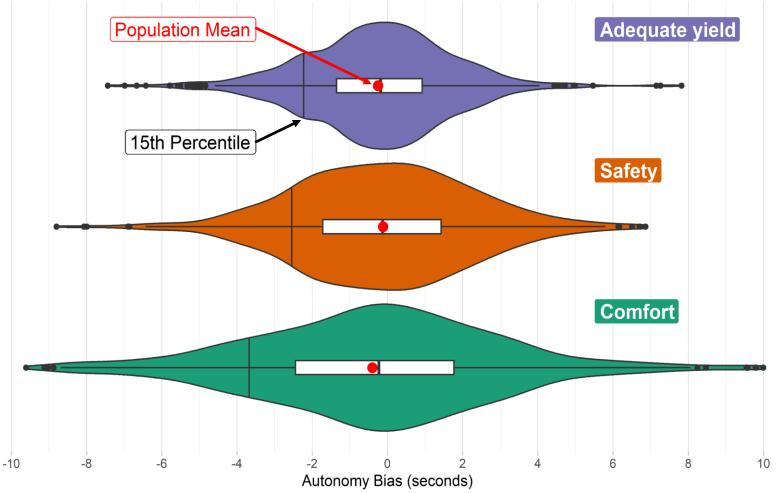






- All three means of Autonomy Bias are • slightly **negative** (>95% confidence), indicating that the BC population has a bias against SDVs (i.e., perceives SDVs less favourably than HDVs)
- Autonomy Bias (comfort) has the largest • magnitude and variability
- For 85% of the population to feel as ٠ comfortable with SDVs as HDVs, SDVs would need to give at least 3.7 seconds more than HDVs when interacting with pedestrians

Three indicators of Autonomy Bias expressed in terms of equivalent passing time (change in time gap between road users that has an equivalent effect on adequate yield, safety, and comfort perceptions)

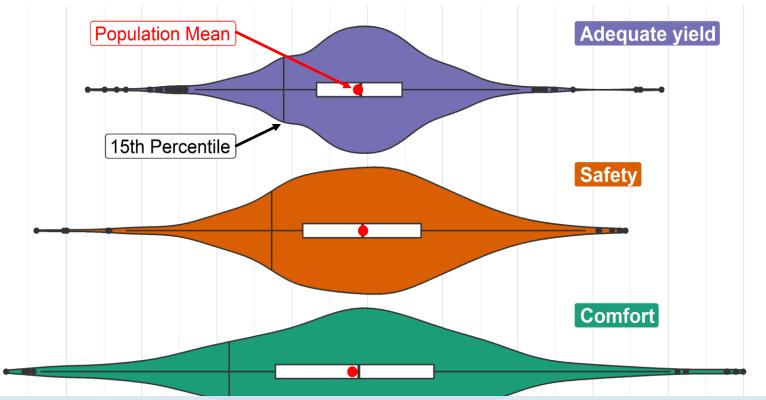


Negative values indicate SDVs needing more passing time than HDVs to obtain the same level of perceived adequate yield, safety, or comfort as HDV

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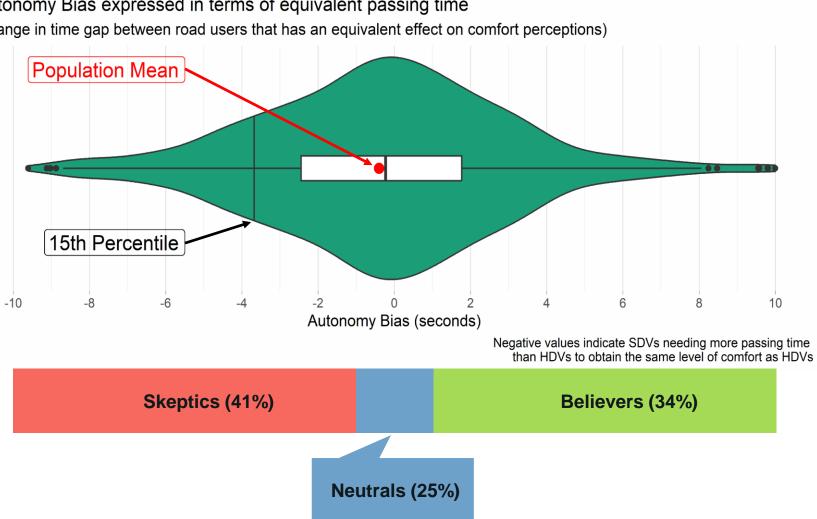
Finding: Both **positive** and **negative** Autonomy Biases exist, **varying substantially** across BC residents, who have a small but significant negative mean bias

Three indicators of Autonomy Bias expressed in terms of equivalent passing time (change in time gap between road users that has an equivalent effect on adequate yield, safety, and comfort perceptions)



Divided BC population into 3 groups based on Autonomy Bias (comfort):

- **Skeptics:** People who have a bias • against SDVs (negative Autonomy Bias)
- Neutrals: People who have no bias towards SDVs
- **Believers:** People who have a ٠ bias in favour of SDVs (positive Autonomy Bias)



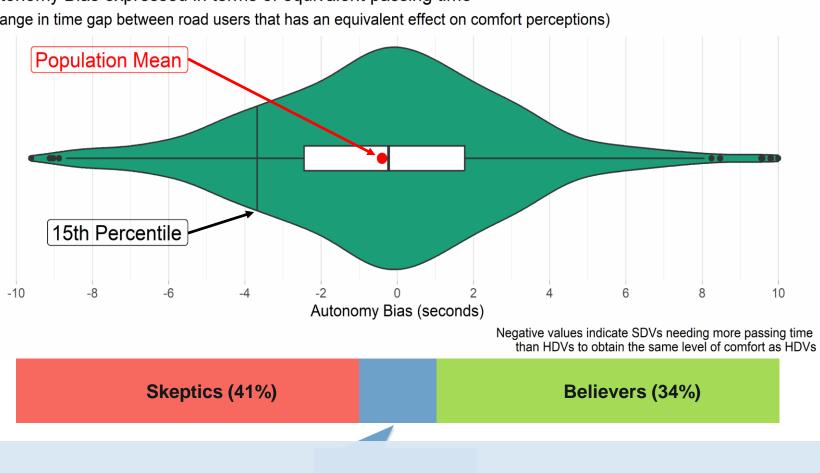
Autonomy Bias expressed in terms of equivalent passing time (change in time gap between road users that has an equivalent effect on comfort perceptions)

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- **Skeptics:** People who have a bias . against SDVs (negative Autonomy Bias)
- Neutrals: People who have no bias towards SDVs
- **Believers:** People who have a •

Finding: More people in the population (41%) are Skeptics, compared to 34% Believers; a substantial portion (25%) are Neutrals (their bias is smaller than 1 second equivalent passing time)

Autonomy Bias expressed in terms of equivalent passing time (change in time gap between road users that has an equivalent effect on comfort perceptions)



- People who are anxious about SDV development
- People who are uncomfortable embracing new technology
- People who are cis-men

This negative bias would tend to degrade their walking experience

more likely to have a bias against SDVs What increases Autonomy Bias? (i.e., makes SDVs more favourable)

Increasing **enthusiasm** about SDVs

Increasing **comfort** in embracing technology

Not a cis-man









- People who are anxious ٠ about SDV development
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more likely to have a bias against SDVs

What increases Autonomy Bias? (i.e., makes SDVs more favourable)

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Not a cis-man

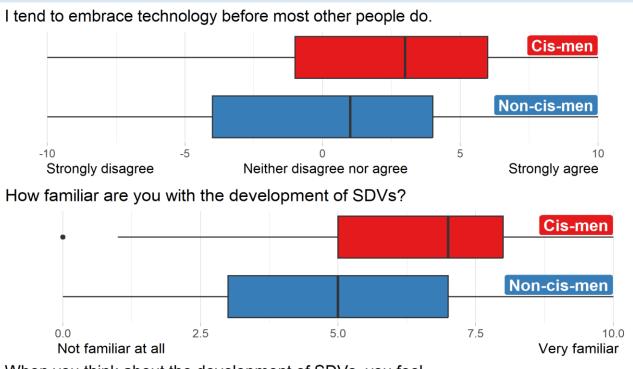
This negative bias would tend to degrade their walking avnarianaa

Finding: Autonomy Bias varies systematically with gender, tech savviness, and affective response to SDV (level of anxiety or enthusiasm), but not with other socio-demographic factors or travel habits.

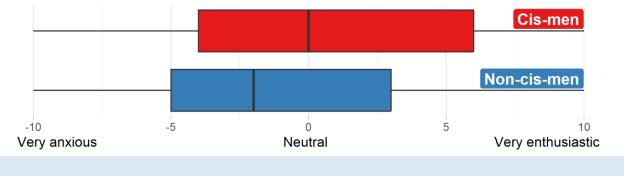


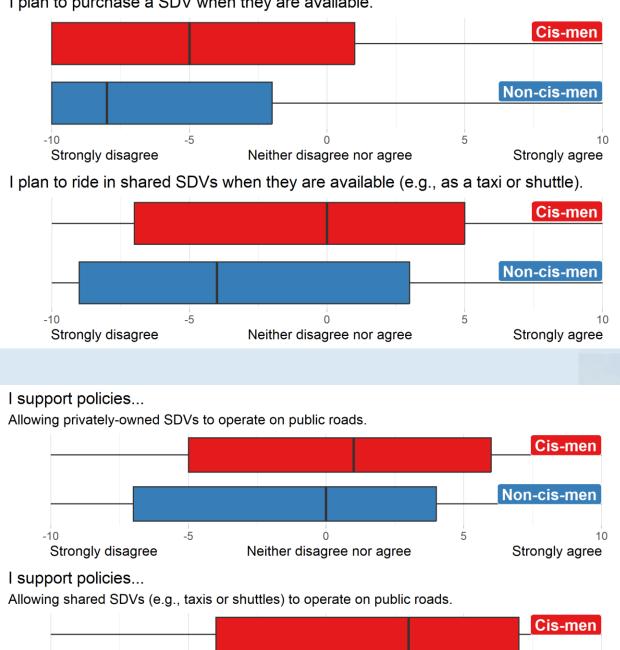
I plan to purchase a SDV when they are available.

INTERESTINGLY, CIS-MEN ARE MORE LIKELY TO HAVE A NEGATIVE AUTONOMY BIAS YET **REPORT POSITIVE ATTITUDES TOWARDS SDVs**



When you think about the development of SDVs, you feel...





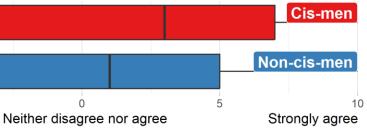
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-5

-10

Strongly disagree

Finding: Observed and self-reported relationships between gender and SDVs are inconsistent



Allowing shared SDVs (e.g., taxis or 55% of population agrees shuttles) to operate on public roads general policies Allowing privately-owned SDVs to 48% operate on public roads or shared SDVs to operate on public roads Allowing SDVs to travel at the same 42% speed as HDVs Allowing SDVs to enter pedestrian There is strong support for 28% priority areas, such as near schools specific SDV restrictions — a large majority of population Allowing SDVs to operate without a 11% does not favour SDVs to operate person in the driver's seat near pedestrian areas, without a "driver", Allowing SDVs to operate without being 8% or without clear identification clearly identified to other road users

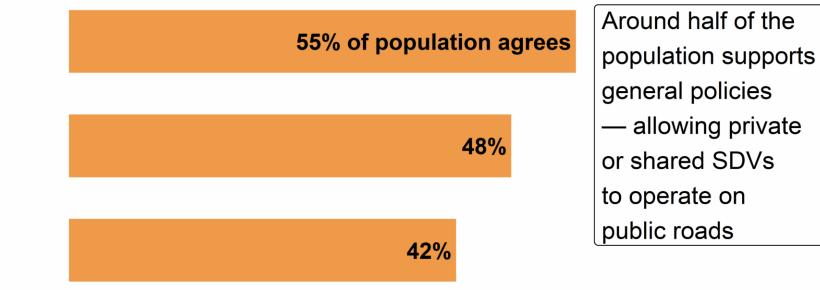
Around half of the population supports — allowing private



Allowing shared SDVs (e.g., taxis or shuttles) to operate on public roads

Allowing privately-owned SDVs to operate on public roads

Allowing SDVs to travel at the same speed as HDVs



Findings: Similar to Autonomy Bias, **BC residents are close to evenly split** on whether they support two general SDV policies: allowing privately-owned or shared SDVs to operate on public roads

In contrast to support for general policies, there is strong support for specific SDV restrictions - a large majority of BC residents want SDVs to be clearly identified, have a human "driver" present, and be restricted from entering pedestrian dominated areas such as near schools



RESULTS	SDV policies	Factors increasing policy s
Finding: Being enthusiastic about SDVs determines SDVs policy support	Allowing shared SDVs (e.g., taxis or shuttles) to operate on public roads	Being enthusiastic about SDVs Being younger than 40 Increasing Autonomy Bia
	Allowing privately-owned SDVs to operate on public roads	Being enthusiastic about SDVs Being tech Riding an automobile often Being younger than
	Allowing SDVs to travel at the same speed as HDVs	Being enthusiastic about S Increasing Autonomy Bias Living outside low
	Allowing SDVs to enter pedestrian priority areas, such as near schools	Being enthusiastic about SDVs Increasing Aut Driving an automobile often
	Allowing SDVs to operate without a person in the driver's seat	Being enthusiastic about S
		Being a cis-man Being
	Allowing SDVs to operate without being clearly identified to other road users	Being enthusiastic about SDVs Living outside lower mainlan

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	RESULTS	SDV policies	Factors increasing policy s
		Allowing shared SDVs (e.g., taxis or shuttles) to operate on public roads	Being enthusiastic about SDVs Being younger than 40 Increasing Autonomy Bias
	Finding: SDV-related factors – being	Allowing privately-owned SDVs to operate on public roads	Being enthusiastic about SDVs Being tech Riding an automobile often Being younger than
enthusiastic about SDVs and having a more	Allowing SDVs to travel at the same speed as HDVs	Being enthusiastic about S Increasing Autonomy Bias Living outside low	
	positive Autonomy Bias – determine SDV policy	Allowing SDVs to enter pedestrian priority areas, such as near schools	Being enthusiastic about SDVs Increasing Auto Driving an automobile often
	support most consistently	Allowing SDVs to operate without a person in the driver's seat	Being enthusiastic about S Being a cis-man Being w
		Allowing SDVs to operate without being clearly identified to other road users	Being enthusiastic about SDVs Living outside lower mainland

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RESULTS	SDV policies	Factors increasing policy s
Findings: But socio -	Allowing shared SDVs (e.g., taxis or shuttles) to operate on	Being enthusiastic about SDVs
demographic factors still persist	public roads	Being younger than 40 Increasing Autonomy Bia
 Older people are less likely to favour 	Allowing privately-owned SDVs to operate on public roads	Being enthusiastic about SDVs Being tech Riding an automobile often Being younger than
shared SDVs	Allowing SDVs to travel at the	Being enthusiastic about S
People of colour	same speed as HDVs	Increasing Autonomy Bias Living outside low
and non-cis-men want to restrict SDVs from operating without a "driver"	Allowing SDVs to enter pedestrian priority areas, such as near schools	Being enthusiastic about SDVs Increasing Aut Driving an automobile often
 People with less auto mobility want 	Allowing SDVs to operate without a person in the driver's seat	Being enthusiastic about S Being a cis-man Being w
to restrict SDVs from going into pedestrian priority areas	Allowing SDVs to operate without being clearly identified to other road users	Being enthusiastic about SDVs Living outside lower mainlan

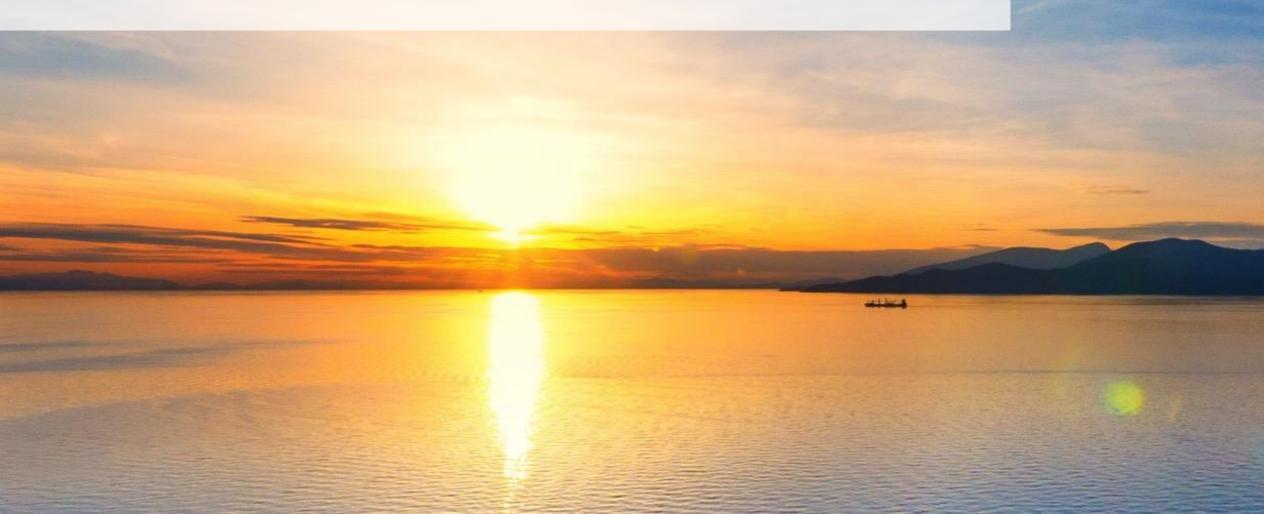
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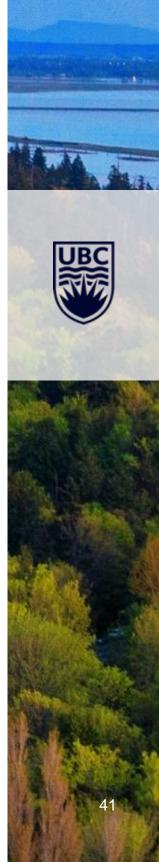
RECOMMENDATIONS





RECOMMENDATIONS (A CAUTIOUS, TIERED APPROACH)

- We recommend a cautious, tiered approach to SDV introduction, starting with pilot testing. •
- Testing should be conducted with **specific restrictions** to address the concerns of BC residents. ۲
- This recommendation is based on: •
 - the demonstrated potential for SDV to **both positively and negatively** impact perceptions of safety and comfort for pedestrians
 - the divided support for SDV introduction
 - the strong support for SDV restrictions



RECOMMENDATIONS (GUIDELINES FOR PILOT TESTING)

- Introduction should begin with **restrictive pilot testing**, which will allow road users to experience and • observe interactions with SDVs in more limited and controlled settings.
- **SDVs should be programmed to operate more conservatively** than HDVs around pedestrians to ٠ ensure comfort
 - SDVs must allow 3.7 seconds additional passing time at crosswalks than typical HDVs to offset the Autonomy Bias of 85% of the population.
- SDVs should be required to have **external communication features** that, at the least, inform other road ٠ users that the motor vehicle they are interacting with is self-driven.
- SDVs should be required to have a person in the driver's seat to take control of the vehicle in ۲ emergencies, and provide interacting road users a familiar human presence with an oversight function.
- SDVs should not be initially tested in pedestrian priority areas such as near schools. •



RECOMMENDATIONS (PILOT TESTING **INTRODUCTION**)

- Opportunities should be provided to the public to gain knowledge about SDV technology, operations, and performance.
- Familiarity with SDVs from SDV experience (during pilot testing) and gaining knowledge leads to **more** enthusiasm, which in turn leads to favourable perceptions of SDVs (i.e., positive Autonomy Bias) and increases support for "pro-SDV" policies.
- Public **feedback should be sought** through surveys, interviews, and focus groups to evaluate the level of • comfort and policy support of road users before, during, and after pilot testing of SDVs.
- If the perceptions of a reasonably large proportion of the public **shift toward comfort**, then SDV • restrictions can be eased accordingly





THE UNIVERSITY OF BRITISH COLUMBIA

Thank you!

For any questions, contact Dr. Alex Bigazzi at abigazzi@ubc.civil.ca

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We would also like to acknowledge the time and valuable input from all the survey participants.

